
Vortex2D Documentation

Release 1.0

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CHAPTER 1

2D real-time fluid engine

1.1 Introduction

This is a 2D engine with the goal of being used in real-time scenarios, e.g. video games, in the same manner as a Box2D.

It is a hybrid engine that uses particles for the advection part (moving the particles given their velocities) and a grid to resolve the incompressible constraints. However, the particles are not visible to the user and you only work with the grid directly.

The engine runs directly on the GPU using Vulkan compute shaders. The rendering is then also done with Vulkan. The grids are represented by textures and operations by the user are all done by drawing shapes on the textures. The engine itself is written in C++ and it provides a simple wrapper around Vulkan and the basic rendering functionalities: shapes, textures, sprites, blending, render textures, etc.

1.2 Table of content

1.2.1 Setup

Vortex2D is multi-platform and currently supports the following:

- Windows
- Linux
- macOS
- iOS

CMake is used to generate the appropriate build scripts for each platform. The dependencies, which are fetched when calling cmake, are **glm** and **SPIRV-cross**. The tests use **gtest** and the examples use **glfw**.

The only dependency required is python. There are several variables that can be used to configure:

CMake	Builds
VORTEX2D_ENABLE_TESTS	builds the tests
VORTEX2D_ENABLE_EXAMPLES	builds the examples
VORTEX2D_ENABLE_DOCS	builds the documentation

The main library is built as a dll on windows, shared library on linux and (dynamic) framework on macOS/iOS.

Prerequisite

Following are necessary:

- Python
- glslangValidator (comes with Vulkan SDK)

Windows

To build on windows, *cmake-gui* is the easiest to use. Only the variables specified above should be changed.

Linux

Again, regular cmake commands should be use to configure cmake:

```
cmake ..
```

macOS

In addition to the normal variables, we need to specify the location of MoltenVK:

```
cmake .. -DMOLTENVK_DIR=../../MoltenVK/Package/Latest/MoltenVK/ -DVORTEX2D_ENABLE_  
EXAMPLES=On
```

iOS

The framework needs to signed on iOS, so the following variables need to be defined:

Variable	Value
CODE_SIGN_IDENTITY	“iPhone Developer”
DEVELOPMENT_TEAM_ID	set to the team id, can be found on the apple developer portal

In addition, the MoltenVK location has to be specified, and the toolchain:

```
cmake .. -DCMAKE_TOOLCHAIN_FILE=../cmake/ios.toolchain.cmake -DIOS_PLATFORM=OS -DIOS_  
ARCH=arm64 -DENABLE_VISIBILITY=true -DMOLTENVK_DIR=../../MoltenVK/Package/Latest/  
MoltenVK/ -DCODE_SIGN_IDENTITY="iPhone Developer" -DDEVELOPMENT_TEAM_ID=XXXXXX
```

Documentation

To build the documentation the following is required:

- doxygen
- sphinx
- sphinx_rtd_theme
- sphinx_breathe

1.2.2 Rendering

Initialization

The rendering API is very basic and supports only the most basic functionality.

Create an instance of `Vortex2D::Renderer::Instance` which is then used to create an instance of `Vortex2D::Renderer::Device`.

The device is then used to create any other object. The main one is the `Vortex2D::Renderer::RenderWindow` which is a window where to render sprites and polygons. The function `Vortex2D::Fluid::RenderWindow::Display()` is then used to present the result to the screen.

```
Vortex2D::Renderer::Instance instance("Application name", extensions); // pass list
// of required extensions
Vortex2D::Renderer::Device device(instance.GetPhysicalDevice(), surface);

Vortex2D::Renderer::RenderWindow window(device, surface, width, height);
```

Note that the instance requires a list of extensions necessary to create a window. With GLFW they can be retrieved as:

```
std::vector<const char*> GetGLFWExtensions()
{
    std::vector<const char*> extensions;
    unsigned int glfwExtensionCount = 0;
    const char** glfwExtensions;

    // get the required extensions from GLFW
    glfwExtensions = glfwGetRequiredInstanceExtensions(&glfwExtensionCount);
    for (unsigned int i = 0; i < glfwExtensionCount; i++)
    {
        extensions.push_back(glfwExtensions[i]);
    }

    return extensions;
}
```

In addition, you also need to create a surface which can be also done with the help of GLFW:

```
vk::UniqueSurfaceKHR GetGLFWSurface(GLFWwindow* window, vk::Instance instance)
{
    // create surface
    VkSurfaceKHR surface;
    if (glfwCreateWindowSurface(static_cast<VkInstance>(instance), window, nullptr, &
    surface) != VK_SUCCESS)
    {
```

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```
    throw std::runtime_error("failed to create window surface!");
}

return vk::UniqueSurfaceKHR(surface, vk::SurfaceKHRDeleter{instance});
}
```

Render Targets

To be able to render, we need to record `Vortex2D::Renderer::RenderCommand` on a `Vortex2D::Renderer::RenderTarget`. There are two implementations of it:

- `Vortex2D::Renderer::RenderWindow`
- `Vortex2D::Renderer::RenderTexture`

You can render implementations of the abstract class `Vortex2D::Renderer::Drawable`, which get recorder in the render command. To actually render it on the render target, the submit function needs to be called. Note, it can be called repeatedly (e.g. over several frames).

In addition, the blend state needs to be passed in, see `Vortex2D::Renderer::ColorBlendState`.

Shapes

We are now ready to draw things on the screen. Let's start with some shapes like rectangles and circles:

```
Vortex2D::Renderer::Rectangle rectangle(device, {100.0f, 100.0f});
Vortex2D::Renderer::Ellipse circle(device, {50.0f, 50.0f});

auto blendMode = vk::PipelineColorBlendAttachmentState()
    .setBlendEnable(true)
    .setAlphaBlendOp(vk::BlendOp::eAdd)
    .setColorBlendOp(vk::BlendOp::eAdd)
    .setSrcColorBlendFactor(vk::BlendFactor::eSrcAlpha)
    .setSrcAlphaBlendFactor(vk::BlendFactor::eOne)
    .setDstColorBlendFactor(vk::BlendFactor::eOneMinusSrcAlpha)
    .setDstAlphaBlendFactor(vk::BlendFactor::eZero);

// note that rectangle, circle and render need to be alive for the duration of the
// rendering
auto render = renderTarget.Record({rectangle, circle}, blendMode);
render.Submit();
```

Textures

Of course we can also render textures, using sprites.

```
Vortex2D::Renderer::Texture texture(device, 100, 100, vk::Format::eR8G8B8A8Unorm);
Vortex2D::Renderer::Sprite sprite(device, texture);
```

Transformations

The shapes and textures can be positioned, i.e. are transformable. You can set the following properties on them:

- Position
- Scale
- Rotation
- Anchor

As an example:

```
Vortex2D::Renderer::Ellipse circle(device, {50.0f, 50.0f});
circle.Colour = {0.0f, 0.0f, 1.0f, 1.0f};
circle.Position = {500.0f, 400.0f};
```

1.2.3 Level sets

A level set is a signed distance field. It's a field containing positive or negative value, where the values are 0 represent a contour, or border. This is used to represent shapes, the numbers give you the distance to the shape border. It's the fundamental way that we represent the area of a fluid and the area of the obstacles, i.e. the boundaries.

The level set is represented simply as a float texture. To set the level set, we simply render on that texture. This means that the class `Vortex2D::Fluid::LevelSet` inherits `Vortex2D::Renderer::RenderTexture`.

Basic shapes

There is a list of basic shapes that can be used to render on a level set:

- `Vortex2D::Fluid::Rectangle`
- `Vortex2D::Fluid::Polygon`
- `Vortex2D::Fluid::Circle`

They are used the same way as regular drawable shapes, i.e.

```
Vortex2D::Fluid::Rectangle rectangle(device, {100.0f, 100.0f});
rectangle.Position = {40.0f, 60.0f};

Vortex2D::Fluid::LevelSet levelSet(device, {400, 400});
auto renderCmd = levelSet.Record({rectangle});
renderCmd.Submit(); // note that renderCmd and rectangle have to be alive until the
// rendering is done
```

Combining shapes

Multiple shapes can be combined together to build the level set. You can either take the union or the intersection when rendering. This happens by using certain blend states which are:

- `Vortex2D::Renderer::IntersectionBlend`
- `Vortex2D::Renderer::UnionBlend`

After combining several shapes, the resulting float texture is not a signed distance field. It needs to be reinitialised which is simply done by calling `Vortex2D::Fluid::LevelSet::Reinitialise()`.

1.2.4 World

The world classes are the centre of the engine, where the fluid gets animated. They contain essentially three fields:

- The velocity field
- The liquid phi field
- The solid phi field

The first one contains the velocity of the fluid at every point, the second one defines where the fluid is. This is a signed distance field where a negative value indicates this is a fluid location. Finally the last one contains the location of solid obstacles, again as a signed distance field where the negative values indicate the solid's location.

Each can be visualised as a texture with the getters:

```
Renderer::RenderTexture& GetVelocity();
DistanceField LiquidDistanceField();
DistanceField SolidDistanceField();
```

Of course, to get interesting fluid simulations, we need to set values on them. Setting the signed distance fields is straightforward (see [Level sets](#)):

```
Renderer::RenderCommand_
    ↵RecordLiquidPhi(Renderer::RenderTarget::DrawableList drawables);
Renderer::RenderCommand_
    ↵RecordStaticSolidPhi(Renderer::RenderTarget::DrawableList drawables);
```

Note that this only has to be done once.

For velocities however, the simulation needs to set the velocities at a specific time during the simulation, so instead of ourselves calling `Vortex2D::Renderer::RenderCommand::Submit()` we pass the `Vortex2D::Renderer::RenderCommand()` to the `World::Fluid::World()` class:

```
Renderer::RenderCommand_
    ↵RecordVelocity(Renderer::RenderTarget::DrawableList drawables);
void SubmitVelocity(Renderer::RenderCommand& renderCommand);
```

Smoke World

This is a type of fluid simulation where the fluid area doesn't move.

Water World

This is a classical water type of fluid simulation.

1.2.5 Rigid body

Rigid bodies are the way to have dynamic interactions with the fluid (other than changing the velocity field directly). Vortex2D only provides a way to get current forces applied to the rigidbodies, and applying velocities from the rigidbody to the fluid. Updating the rigidbody's forces, velocities and position needs to be done by a separate engine, such as Box2D.

Rigidbodies have three types:

- Static

- Weak
- Strong

Static bodies

Static bodies act on the fluid, but the fluid doesn't act on the fluid. They have a velocity that is imparted on the fluid. Think of motorized objects pushing through the fluid.

Weak/Strong bodies

Weak rigidbodies are affected by the fluid. They can also in turn, affect the fluid, which is called a strong coupling with the fluid.

1.2.6 Renderer API reference

Classes

- `Vortex2D::Renderer::Clear`
- `Vortex2D::Renderer::Drawable`
- `Vortex2D::Renderer::Ellipse`
- `Vortex2D::Renderer::GenericBuffer`
- `Vortex2D::Renderer::IndirectBuffer`
- `Vortex2D::Renderer::Instance`
- `Vortex2D::Renderer::IntRectangle`
- `Vortex2D::Renderer::Rectangle`
- `Vortex2D::Renderer::RenderState`
- `Vortex2D::Renderer::RenderTarget`
- `Vortex2D::Renderer::RenderTexture`
- `Vortex2D::Renderer::RenderWindow`
- `Vortex2D::Renderer::Sprite`
- `Vortex2D::Renderer::Timer`
- `Vortex2D::Renderer::Transformable`
- `Vortex2D::Renderer::UniformBuffer`
- `Vortex2D::Renderer::VertexBuffer`
- `Vortex2D::Renderer::Work`

API Reference

```
namespace Renderer
```

Typedefs

```
using Vortex2D::Renderer::DescriptorTypeBindings = typedef std::map<uint32_t, vk::DescriptorType>
typedef std::vector<glm::vec2> Path
```

Functions

VORTEX2D_API void Vortex2D::Renderer::BufferBarrier(vk::Buffer buffer, vk::CommandBuffer commandBuffer)
Inserts a barrier for the given buffer, command buffer and access.

Parameters

- `buffer`: the vulkan buffer handle
- `commandBuffer`: the command buffer to inserts the barrier
- `oldAccess`: old access
- `newAccess`: new access

```
template <template< typename > class BufferType, typename T>
void CopyTo (BufferType<T> &buffer, T &t)
    Copy the content of a buffer in an object.
```

```
template <template< typename > class BufferType, typename T>
void CopyTo (BufferType<T> &buffer, std::vector<T> &t)
    Copy the content of a buffer to a vector. Vector needs to have the correct size already.
```

```
template <template< typename > class BufferType, typename T>
void CopyFrom (BufferType<T> &buffer, const T &t)
    Copy the content of an object to the buffer.
```

```
template <template< typename > class BufferType, typename T>
void CopyFrom (BufferType<T> &buffer, const std::vector<T> &t)
    Copy the content of a vector to the buffer.
```

void VORTEX2D_API Vortex2D::Renderer::ExecuteCommand(const Device & device, CommandBuffer commandBuffer)
Runs immediately a set of commands and waits for them to finish.

Parameters

- `device`: vulkan device
- `commandFn`: lambda that runs the commands.

```
bool operator== (const ShaderLayout &left, const ShaderLayout &right)
```

```
bool operator== (const PipelineLayout &left, const PipelineLayout &right)
```

```
vk::DescriptorType GetDescriptorType (uint32_t bind, const PipelineLayout &layout)
```

VORTEX2D_API void Vortex2D::Renderer::Bind(const Device & device, vk::DescriptorSet descriptorSet)
Bind the resources (buffer or texture/sampler) to a [DescriptorSet](#).

Parameters

- `device`: vulkan device
- `dstSet`: vulkan descriptor set

- layout: pipeline layout
- bindingInputs: list of resources (buffer or texture/sampler)

```
bool HasLayer(const char *extension, const std::vector<vk::LayerProperties> &availableExtensions)
```

```
bool HasExtension(const char *extension, const std::vector<vk::ExtensionProperties> &availableExtensions)
```

VORTEX2D_API `vk::UniquePipeline` `Vortex2D::Renderer::MakeComputePipeline(vk::Device device`
Create a compute pipeline.

Return compute pipeline

Parameters

- device: vulkan device
- shader: shader module
- layout: layout of shader
- specConstInfo: any specialisation constants

```
template <typename Type>
SpecConstInfo::Value<Type> SpecConstValue(uint32_t id, Type &&value)
```

Constructs a specialization constant value.

```
template <typename... Args>
SpecConstInfo SpecConst(Args&&... args)
```

Constructs a `SpecConstInfo` with given values of specialisation constants.

```
bool operator==(const RenderState &left, const RenderState right)
```

VORTEX2D_API `ComputeSize` `Vortex2D::Renderer::MakeStencilComputeSize(const glm::ivec2 &`
Create a `ComputeSize` for a stencil type shader.

Return calculate `ComputeSize`

Parameters

- size: the domain size
- radius: the stencil size

VORTEX2D_API `ComputeSize` `Vortex2D::Renderer::MakeCheckerboardComputeSize(const glm::ivec2 &`

Create a `ComputeSize` for a checkerboard type shader.

Return calculate `ComputeSize`

Parameters

- size: the domain size

```
class AbstractShape : public Vortex2D::Renderer::Drawable, public Vortex2D::Renderer::Transformable
#include <Shapes.h> An polygonal shape where the fragment shader can be specified for customisation.
```

Subclassed by `Vortex2D::Renderer::IntRectangle`, `Vortex2D::Renderer::Rectangle`

Public Functions

```
AbstractShape(const Device &device, const SpirvBinary &fragShader, const  
std::vector<glm::vec2> &vertices)  
AbstractShape(AbstractShape &&other)  
virtual VORTEX2D_API ~AbstractShape()  
void Initialize(const RenderState &renderState)
```

Initialize the drawable for a particular state. This might include creating the correct pipeline. If it was already initialized, it will do nothing.

Parameters

- renderState: the state to initialize with.

```
void Update(const glm::mat4 &projection, const glm::mat4 &view)  
Update the MVP matrix of the drawable.
```

Parameters

- projection: the projection matrix
- view: the view matrix

```
void Draw(vk::CommandBuffer commandBuffer, const RenderState &renderState)  
Draw for the given render state. This has to be initialized before.
```

Parameters

- commandBuffer: the command buffer to record into.
- renderState: the render state to use.

Public Members

glm::vec4 Colour

```
class AbstractSprite : public Vortex2D::Renderer::Drawable, public Vortex2D::Renderer::Transformable  
#include <Sprite.h> a Sprite, i.e. a drawable that can render a texture. The fragment shader can be  
specified for customisation.
```

Subclassed by *Vortex2D::Fluid::DistanceField*, *Vortex2D::Renderer::Sprite*

Public Functions

```
AbstractSprite(const Device &device, const SpirvBinary &fragShaderName, Texture  
&texture)
```

```
AbstractSprite(AbstractSprite &&other)
```

```
virtual VORTEX2D_API ~AbstractSprite()
```

```
void Initialize(const RenderState &renderState)
```

Initialize the drawable for a particular state. This might include creating the correct pipeline. If it was already initialized, it will do nothing.

Parameters

- renderState: the state to initialize with.

```
void Update (const glm::mat4 &projection, const glm::mat4 &view)
    Update the MVP matrix of the drawable.
```

Parameters

- **projection**: the projection matrix
- **view**: the view matrix

```
void Draw (vk::CommandBuffer commandBuffer, const RenderState &renderState)
    Draw for the given render state. This has to be initialized before.
```

Parameters

- **commandBuffer**: the command buffer to record into.
- **renderState**: the render state to use.

```
template <typename T>
void PushConstant (vk::CommandBuffer commandBuffer, uint32_t offset, const T &data)
```

Public Members

```
glm::vec4 Colour = {1.0f, 1.0f, 1.0f, 1.0f}
```

struct BindingInput

```
#include <DescriptorSet.h> The texture/sampler or buffer that can be binded to a shader.
```

Public Functions

```
BindingInput (Renderer::GenericBuffer &buffer, uint32_t bind = DefaultBind)
```

```
BindingInput (Renderer::Texture &texture, uint32_t bind = DefaultBind)
```

```
BindingInput (vk::Sampler sampler, Renderer::Texture &texture, uint32_t bind = DefaultBind)
```

Public Members

```
uint32_t Bind
```

```
mapbox::util::variant<Renderer::GenericBuffer *, DescriptorImage> Input
```

Public Static Attributes

```
constexpr uint32_t DefaultBind = static_cast<uint32_t>(-1)
```

template <typename T>**class Buffer** : **public** Vortex2D::Renderer::GenericBuffer

```
#include <Buffer.h> a storage buffer type of buffer
```

Public Functions

```
Buffer (const Device &device, std::size_t size = 1, VmaMemoryUsage memoryUsage =
    VMA_MEMORY_USAGE_GPU_ONLY)
```

class Clear : **public** Vortex2D::Renderer::Drawable

```
#include <Shapes.h> A drawable that simply clears the target.
```

Public Functions

```
clear (const glm::vec4 &colour)
```

```
void Initialize (const RenderState &renderState)
```

Initialize the drawable for a particular state. This might include creating the correct pipeline. If it was already initialized, it will do nothing.

Parameters

- renderState: the state to initialize with.

```
void Update (const glm::mat4 &projection, const glm::mat4 &view)
```

Update the MVP matrix of the drawable.

Parameters

- projection: the projection matrix
- view: the view matrix

```
void Draw (vk::CommandBuffer commandBuffer, const RenderState &renderState)
```

Draw for the given render state. This has to be initialized before.

Parameters

- commandBuffer: the command buffer to record into.
- renderState: the render state to use.

```
struct ColorBlendState
```

#include <RenderState.h> The blend state and blend constant.

Public Functions

```
ColorBlendState()
```

Public Members

```
vk::PipelineColorBlendAttachmentState ColorBlend
```

```
std::array<float, 4> BlendConstants
```

```
class CommandBuffer
```

#include <CommandBuffer.h> Can record commands, then submit them (multiple times). A fence can be used to wait on the completion of the commands.

Public Types

```
using CommandFn = std::function<void (vk::CommandBuffer)>
```

Public Functions

```
CommandBuffer (const Device &device, bool synchronise = true)
```

Creates a command buffer which can be synchronized.

Parameters

- device: vulkan device

- `synchronise`: flag to determine if the command buffer can be waited on.

```
~CommandBuffer()

CommandBuffer(CommandBuffer &&other)

CommandBuffer &operator=(CommandBuffer &&other)

void Record(CommandFn commandFn)
    Record some commands. The commands are recorded in the lambda which is immediately executed.

Parameters
    • commandFn: a functor, or simply a lambda, where commands are recorded.

void Record(const RenderTarget &renderTarget, vk::Framebuffer framebuffer, CommandFn
           commandFn)
    Record some commands inside a render pass. The commands are recorded in the lambda which is
    immediately executed.

Parameters
    • renderTarget: the render target which contains the render pass to record into
    • framebuffer: the frame buffer where the render pass will render.
    • commandFn: a functor, or simply a lambda, where commands are recorded.

void Wait()
    Wait for the command submit to finish. Does nothing if the synchronise flag was false.

void Reset()
    Reset the command buffer so it can be recorded again.

void Submit(const std::initializer_list<vk::Semaphore> &waitSemaphores = {}, const
           std::initializer_list<vk::Semaphore> &signalSemaphores = {})
    submit the command buffer

operator bool() const
    explicit conversion operator to bool, indicates if the command was properly recorded and can be
    submitted.

struct ComputeSize
    #include <Work.h> Used for a compute shader, and defines the group size, local size and domain size.
```

Public Functions

```
ComputeSize(const glm::ivec2 &size, const glm::ivec2 &localSize = GetLocalSize2D())
    Creates a ComputeSize using a 2D domain size and the default 2D local size.
```

Parameters

- `size`: the domain size
- `localSize`: the local size of the shader

```
ComputeSize(int size, int localSize = GetLocalSize1D())
    Creates a ComputeSize using a 1D domain size and the default 1D local size.
```

Parameters

- `size`: the domain size
- `localSize`: the local size of the shader

Public Members

```
glm::ivec2 DomainSize  
glm::ivec2 WorkSize  
glm::ivec2 LocalSize
```

Public Static Functions

```
glm::ivec2 GetLocalSize2D()
```

The default local size for 2D compute shaders.

Return a 2d vector

```
int GetLocalSize1D()
```

The default local size for 1D compute shaders.

Return a integer value

```
glm::ivec2 GetWorkSize(const glm::ivec2 &size, const glm::ivec2 &localSize = GetLocal-  
Size2D())
```

Computes the 2D group size given a domain size.

Return the group size

Parameters

- `size`: the domain size of the shader
- `localSize`: the local size of the shader

```
glm::ivec2 GetWorkSize(int size, int localSize = GetLocalSize1D())
```

Computes the 1D group size given a domain size.

Return the group size

Parameters

- `size`: the domain size of the shader
- `localSize`: the local size of the shader

```
ComputeSize Default2D()
```

A default `ComputeSize` using the default 2D local size. The domain size is (1,1)

Return a default compute size

```
ComputeSize Default1D()
```

A default `ComputeSize` using the default 1D local size. The domain size is (1,1)

Return a default compute size

```
struct DescriptorImage
```

#include <DescriptorSet.h> The texture or sampler that can be binded to a shader.

Public Functions

```
DescriptorImage(vk::Sampler sampler, Renderer::Texture &texture)
```

```
DescriptorImage(Renderer::Texture &texture)
```

Public Members

```

vk::Sampler Sampler
Renderer::Texture *Texture

struct DescriptorSet
#include <DescriptorSet.h> The binding of an object for a shader.

```

Public Members

```

vk::UniqueDescriptorSet descriptorSet
vk::PipelineLayout pipelineLayout
vk::DescriptorsetLayout descriptorsetLayout

class Device
#include <Device.h> Encapsulation around the vulkan device. Allows to create command buffers, layout, bindings, memory and shaders.

```

Public Functions

```

Device (vk::PhysicalDevice physicalDevice, bool validation = true)

Device (vk::PhysicalDevice physicalDevice, vk::SurfaceKHR surface, bool validation = true)

Device (vk::PhysicalDevice physicalDevice, int familyIndex, bool validation = true)

~Device()

Device (Device&&)

Device &operator= (Device&&)

vk::Device Handle () const

vk::Queue Queue () const

vk::PhysicalDevice GetPhysicalDevice () const

int GetFamilyIndex () const

std::vector<vk::CommandBuffer> CreateCommandBuffers (uint32_t size) const

void FreeCommandBuffers (vk::ArrayProxy<const vk::CommandBuffer> commandBuffers)
                           const

VmaAllocator Allocator () const

LayoutManager &GetLayoutManager () const

vk::ShaderModule GetShaderModule (const SpirvBinary &spirv) const

struct DispatchParams
#include <Work.h> Parameters for indirect compute: group size, local size, etc.

```

Public Functions

```
DispatchParams (int count)
```

Public Members

```
vk::DispatchIndirectCommand workSize
```

```
uint32_t count
```

struct Drawable

```
#include <Drawable.h> Interface of a drawable object.
```

Subclassed by `Vortex2D::Fluid::Circle`, `Vortex2D::Fluid::Polygon`, `Vortex2D::Renderer::AbstractShape`, `Vortex2D::Renderer::AbstractSprite`, `Vortex2D::Renderer::Clear`, `Vortex2D::Renderer::Ellipse`

Public Functions

```
virtual ~Drawable()
```

```
virtual void Initialize (const RenderState &renderState) = 0
```

Initialize the drawable for a particular state. This might include creating the correct pipeline. If it was already initialized, it will do nothing.

Parameters

- renderState: the state to initialize with.

```
virtual void Update (const glm::mat4 &projection, const glm::mat4 &view) = 0
```

Update the MVP matrix of the drawable.

Parameters

- projection: the projection matrix
- view: the view matrix

```
virtual void Draw (vk::CommandBuffer commandBuffer, const RenderState &renderState) =
```

```
0
```

Draw for the given render state. This has to be initialized before.

Parameters

- commandBuffer: the command buffer to record into.
- renderState: the render state to use.

```
class Ellipse : public Vortex2D::Renderer::Drawable, public Vortex2D::Renderer::Transformable
```

#include <Shapes.h> A solid colour ellipse. Implements the `Drawable` interface and `Transformable` interface.

Public Functions

```
Ellipse (const Device &device, const glm::vec2 &radius)
```

```
void Initialize (const RenderState &renderState)
```

Initialize the drawable for a particular state. This might include creating the correct pipeline. If it was already initialized, it will do nothing.

Parameters

- `renderState`: the state to initialize with.

```
void Update (const glm::mat4 &projection, const glm::mat4 &view)
    Update the MVP matrix of the drawable.
```

Parameters

- `projection`: the projection matrix
- `view`: the view matrix

```
void Draw (vk::CommandBuffer commandBuffer, const RenderState &renderState)
    Draw for the given render state. This has to be initialized before.
```

Parameters

- `commandBuffer`: the command buffer to record into.
- `renderState`: the render state to use.

Public Members

`glm::vec4 Colour`

`class GenericBuffer`

```
#include <Buffer.h> A vulkan buffer which can be on the host or the device.
```

```
Subclassed by Vortex2D::Renderer::Buffer< float >, Vortex2D::Renderer::Buffer< glm::ivec2 >, Vortex2D::Renderer::Buffer< glm::vec2 >, Vortex2D::Renderer::Buffer< int >, Vortex2D::Renderer::Buffer< Vortex2D::Fluid::Particle >, Vortex2D::Renderer::Buffer< Vortex2D::Fluid::RigidBody::Velocity >, Vortex2D::Renderer::Buffer< Vortex2D::Renderer::DispatchParams >, Vortex2D::Renderer::IndirectBuffer< Vortex2D::Renderer::DispatchParams >, Vortex2D::Renderer::UniformBuffer< glm::mat4 >, Vortex2D::Renderer::UniformBuffer< glm::vec2 >, Vortex2D::Renderer::UniformBuffer< glm::vec4 >, Vortex2D::Renderer::UniformBuffer< Size >, Vortex2D::Renderer::UniformBuffer< Vortex2D::Fluid::RigidBody::Velocity >, Vortex2D::Renderer::VertexBuffer< glm::vec2 >, Vortex2D::Renderer::VertexBuffer< Vortex2D::AbstractSprite::Vertex >, Vortex2D::Renderer::Buffer< T >, Vortex2D::Renderer::IndirectBuffer< T >, Vortex2D::Renderer::UniformBuffer< T >, Vortex2D::Renderer::VertexBuffer< T >
```

Public Functions

```
GenericBuffer (const Device &device, vk::BufferUsageFlags usageFlags, VmaMemoryUsage memoryUsage, vk::DeviceSize deviceSize)
```

```
~GenericBuffer ()
```

```
GenericBuffer (GenericBuffer &&other)
```

```
void CopyFrom (vk::CommandBuffer commandBuffer, GenericBuffer &srcBuffer)
    Copy a buffer to this buffer.
```

Parameters

- `commandBuffer`: command buffer to run the copy on.
- `srcBuffer`: the source buffer.

```
void CopyFrom (vk::CommandBuffer commandBuffer, Texture &srcTexture)
    Copy a texture to this buffer.
```

Parameters

- `commandBuffer`: command buffer to run the copy on.
- `srcTexture`: the source texture

`vk::Buffer Handle() const`

The vulkan handle.

`vk::DeviceSize Size() const`

The size in bytes of the buffer.

`void Barrier(vk::CommandBuffer commandBuffer, vk::AccessFlags oldAccess, vk::AccessFlags newAccess)`

Inserts a barrier for this buffer.

Parameters

- `commandBuffer`: the command buffer to run the barrier
- `oldAccess`: old access
- `newAccess`: new access

`void Clear(vk::CommandBuffer commandBuffer)`

Clear the buffer with 0.

Parameters

- `commandBuffer`: the command buffer to clear on

Friends

`template <template< typename > class BufferType, typename T>`

`void CopyFrom(BufferType<T> &buffer, const T &t)`

Copy the content of an object to the buffer.

`template <template< typename > class BufferType, typename T>`

`void CopyTo(BufferType<T> &buffer, T &t)`

Copy the content of a buffer in an object.

`template <template< typename > class BufferType, typename T>`

`void CopyTo(BufferType<T> &buffer, std::vector<T> &t)`

Copy the content of a buffer to a vector. Vector needs to have the correct size already.

`template <template< typename > class BufferType, typename T>`

`void CopyFrom(BufferType<T> &buffer, const std::vector<T> &t)`

Copy the content of a vector to the buffer.

`class GraphicsPipeline`

#include <Pipeline.h> graphics pipeline which caches the pipeline per render states.

Public Functions

`GraphicsPipeline()`

`GraphicsPipeline(Builder builder)`

`void Create(vk::Device device, const RenderState &renderState)`

`void Bind(vk::CommandBuffer commandBuffer, const RenderState &renderState)`

`class Builder`

#include <Pipeline.h> *Builder* for graphics pipeline.

Public Functions

Builder()

GraphicsPipeline::Builder &Shader (vk::ShaderModule *shader*, vk::ShaderStageFlagBits *shaderStage*)

Set the shader.

Return *this

Parameters

- *shader*: the loaded shader
- *shaderStage*: shader state (vertex, fragment or compute)

GraphicsPipeline::Builder &VertexAttribute (uint32_t *location*, uint32_t *binding*, vk::Format *format*, uint32_t *offset*)

Sets the vertex attributes.

Return *this

Parameters

- *location*: location in the shader
- *binding*: binding in the shader
- *format*: vertex format
- *offset*: offset in the vertex

GraphicsPipeline::Builder &VertexBinding (uint32_t *binding*, uint32_t *stride*, vk::VertexInputRate *inputRate* = vk::VertexInputRate::eVertex)

Sets the vertex binding.

Return *this

Parameters

- *binding*: binding in the shader
- *stride*: stride in bytes
- *inputRate*: input rate

GraphicsPipeline::Builder &Topology (vk::PrimitiveTopology *topology*)

GraphicsPipeline::Builder &Layout (vk::PipelineLayout *pipelineLayout*)

vk::UniquePipeline **Create** (vk::Device *device*, **const** *RenderState* &*renderState*)

template <typename *T*>

class IndirectBuffer : **public** Vortex2D::*Renderer*::*GenericBuffer*

#include <Buffer.h> an indirect buffer type of buffer, used for compute indirect dispatch

Public Functions

IndirectBuffer (**const** *Device* &*device*, VmaMemoryUsage *memoryUsage* = VMA_MEMORY_USAGE_GPU_ONLY)

class Instance

#include <Instance.h> Vulkan instance, which extensions enabled.

Public Functions

Instance (**const** std::string &*name*, std::vector<**const** char *> *extensions*, **bool** *validation*)

```
~Instance()

vk::PhysicalDevice GetPhysicalDevice() const

vk::Instance GetInstance() const

class IntRectangle : public Vortex2D::Renderer::AbstractShape
#include <Shapes.h> A solid colour rectangle as Rectangle, however uses integer colors and is meant to
be drawn to a framebuffer with integer colours.
```

Public Functions

```
IntRectangle(const Device &device, const glm::vec2 &size)

class LayoutManager
#include <DescriptorSet.h> Caches and creates layouts and bindings.
```

Public Functions

```
LayoutManager(const Device &device)

void CreateDescriptorPool()
Create or re-create the descriptor pool, will render invalid existing descriptor sets.

DescriptorSet MakeDescriptorSet (const PipelineLayout &layout)
Create the descriptor set given the layout.

Return built descriptor set
Parameters

- layout: pipeline/shader layout



vk::DescriptorsetLayout GetDescriptorsetLayout (const PipelineLayout &layout)
Create, cache and return a descriptor layout given the pipeline layout.

Return cached descriptor set layout
Parameters

- layout: pipeline layout



vk::PipelineLayout GetPipelineLayout (const PipelineLayout &layout)
create, cache and return a vulkan pipeline layout given the layout

Return vulkan pipeline layout
Parameters

- layout: pipeline layout

struct PipelineLayout
#include <DescriptorSet.h> Represents the layout of a pipeline: vertex + fragment or compute.
```

Public Members

```
std::vector<ShaderLayout> layouts

template <typename T>
class property
#include <Transformable.h> Simple class to simulate properties like in C#.
```

Public Functions

```
property (Transformable &t)
T &operator= (const T &i)
operator T const& () const

class Rectangle : public Vortex2D::Renderer::AbstractShape
#include <Shapes.h> A solid colour rectangle defined by two triangles. Implements the Drawable interface and Transformable interface.
```

Public Functions

```
Rectangle (const Device &device, const glm::vec2 &size)
class RenderCommand
#include <CommandBuffer.h> A special command buffer that has been recorded by a RenderTarget. It can be used to submit the rendering. The object has to stay alive until rendering is complete.
```

Public Functions

```
RenderCommand ()
~RenderCommand ()
RenderCommand (RenderCommand &&other)
RenderCommand &operator= (RenderCommand &&other)
RenderCommand &Submit (const glm::mat4 &view = glm::mat4(1.0f))
    Submit the render command with a transform matrix.
Return *this
Parameters
    • view: a transform matrix
void Wait ()
    Wait for the render command to complete.
```

Friends

```
friend Vortex2D::Renderer::RenderTexture
friend Vortex2D::Renderer::RenderWindow

class RenderpassBuilder
#include <RenderTarget.h> Factory for a vulkan render pass.
```

Public Functions

RenderpassBuilder &**Attachment** (`vk::Format format`)

Format of the render pass.

Return

Parameters

- `format`:

RenderpassBuilder &**AttachmentLoadOp** (`vk::AttachmentLoadOp value`)

operation to perform when loading the framebuffer (clear, load, etc)

Return

Parameters

- `value`:

RenderpassBuilder &**AttachmentStoreOp** (`vk::AttachmentStoreOp value`)

operation to perform when storing the framebuffer (clear, save, etc)

Return

Parameters

- `value`:

RenderpassBuilder &**AttachmentInitialLayout** (`vk::ImageLayout layout`)

Layout of the image to be before render pass.

Return

Parameters

- `layout`:

RenderpassBuilder &**AttachmentFinalLayout** (`vk::ImageLayout layout`)

Layout of the image to be after render pass.

Return

Parameters

- `layout`:

RenderpassBuilder &**Subpass** (`vk::PipelineBindPoint bindPoint`)

Define subpass of the render pass.

Return

Parameters

- `bindPoint`:

RenderpassBuilder &**SubpassColorAttachment** (`vk::ImageLayout layout, uint32_t attachment`)

Set the color attachment with index.

Return

Parameters

- `layout`:
- `attachment`: index of the attachment

RenderpassBuilder &**Dependency** (`uint32_t srcSubpass, uint32_t dstSubpass`)

Dependency of the subpasses.

Return

Parameters

- `srcSubpass`:

- dstSubpass:

`RenderpassBuilder &DependencySrcStageMask (vk::PipelineStageFlags value)`

`RenderpassBuilder &DependencyDstStageMask (vk::PipelineStageFlags value)`

`RenderpassBuilder &DependencySrcAccessMask (vk::AccessFlags value)`

`RenderpassBuilder &DependencyDstAccessMask (vk::AccessFlags value)`

`vk::UniqueRenderPass Create (vk::Device device)`

Create the render pass.

Return

Parameters

- device:

struct RenderState

#include <RenderState.h> the various state to render to a target: size, render pass and blend.

Public Functions

RenderState (const RenderTarget &renderTarget)

Initialize for a render target with default blend.

Parameters

- renderTarget:

RenderState (const RenderTarget &renderTarget, ColorBlendState blendState)

Initialize for a render target with a given blend.

Parameters

- renderTarget:
- colorBlend:

Public Members

`uint32_t Width`

`uint32_t Height`

`vk::RenderPass RenderPass`

`ColorBlendState BlendState`

struct RenderTarget

#include <RenderTarget.h> A target that can be rendered to. This is implemented by the `RenderWindow` and the `RenderTarget`.

Subclassed by `Vortex2D::Renderer::RenderTarget`, `Vortex2D::Renderer::RenderWindow`

Public Types

`using DrawableList = std::initializer_list<std::reference_wrapper<Drawable>>`

Public Functions

```
RenderTarget (uint32_t width, uint32_t height)
```

```
RenderTarget (RenderTarget &&other)
```

```
~RenderTarget ()
```

```
virtual VORTEX2D_API RenderCommand Vortex2D::Renderer::RenderTarget::Record(Drawable)
```

```
virtual VORTEX2D_API void Vortex2D::Renderer::RenderTarget::Submit(RenderCommand &
```

Public Members

```
uint32_t Width
```

```
uint32_t Height
```

```
glm::mat4 Orth
```

```
glm::mat4 View
```

```
vk::UniqueRenderPass RenderPass
```

```
class RenderTexture : public Vortex2D::Renderer::RenderTarget, public Vortex2D::Renderer::Texture  
#include <RenderTexture.h> A render target that renders into a texture.
```

Subclassed by *Vortex2D::Fluid::Density*, *Vortex2D::Fluid::LevelSet*, *Vortex2D::Fluid::ParticleCount*, *Vortex2D::Fluid::Velocity*

Public Functions

```
RenderTexture (const Device &device, uint32_t width, uint32_t height, vk::Format format)
```

```
RenderCommand Record (DrawableList drawables, ColorBlendState blendState = {})
```

```
void Submit (RenderCommand &renderCommand)
```

```
class RenderWindow : public Vortex2D::Renderer::RenderTarget  
#include <RenderWindow.h> Render to a swapchain, i.e. to the window/surface.
```

Public Functions

```
RenderWindow (const Device &device, vk::SurfaceKHR surface, uint32_t width, uint32_t  
height)
```

Initialize with a given surface and size.

Parameters

- device: vulkan device
- surface: vulkan surface
- width:
- height:

```
RenderCommand Record (DrawableList drawables, ColorBlendState blendState = {})
```

```
void Submit (RenderCommand &renderCommand)
```

```
void Display()
    Submits all the render command and present the surface for display.

class SamplerBuilder
    #include <Texture.h> Factory for a vulkan sampler.
```

Public Functions

SamplerBuilder()
SamplerBuilder &AddressMode (vk::SamplerAddressMode *mode*)
 Mode of the sampler: repeat, clamp, etc.

Return *this
Parameters
 • mode: vulkan mode

SamplerBuilder &Filter (vk::Filter *filter*)
 Filter of the sampler: linear, nearest, etc.
Return *this
Parameters
 • filter: vulkan filter

vk::UniqueSampler Create (vk::Device *device*)
 Create the vulkan sampler.
Return unique sampler
Parameters
 • device: vulkan device

struct ShaderLayout
 #include <DescriptorSet.h> Represents the layout of a shader (vertex, fragment or compute)

Public Functions

ShaderLayout (**const** SPIRV::Reflection &*reflection*)

Public Members

vk::ShaderStageFlags shaderStage
DescriptorTypeBindings bindings
unsigned pushConstantSize

struct SpecConstInfo
 #include <Pipeline.h> Defines and holds value of the specification constants for shaders.

Public Functions

SpecConstInfo()

Public Members

```
vk::SpecializationInfo info
std::vector<vk::SpecializationMapEntry> mapEntries
std::vector<char> data

template <typename Type>
struct Value
```

Public Members

```
uint32_t id
Type value

class SpirvBinary
#include <Device.h> A binary SPIRV shader, to be feed to vulkan.
```

Public Functions

```
template <std::size_t N>
SpirvBinary (const uint32_t (&spirv)[N])

const uint32_t *data() const
std::size_t size() const
std::size_t words() const

class Sprite : public Vortex2D::Renderer::AbstractSprite
#include <Sprite.h> A sprite that renders a texture with a simple pass-through fragment shader.

Subclassed by Vortex2D::Fluid::Density
```

Public Functions

```
Sprite (const Device &device, Texture &texture)
struct SwapChainSupportDetails
```

Public Functions

```
SwapChainSupportDetails (vk::PhysicalDevice device, vk::SurfaceKHR surface)
bool IsValid() const
```

Public Members

```

vk::SurfaceCapabilitiesKHR capabilities
std::vector<vk::SurfaceFormatKHR> formats
std::vector<vk::PresentModeKHR> presentModes

class Texture
#include <Texture.h> A texture, or in vulkan terms, an image.

Subclassed by Vortex2D::Renderer::RenderTexture

```

Public Functions

```

Texture (const Device &device, uint32_t width, uint32_t height, vk::Format format, VmaMemoryUsage memoryUsage = VMA_MEMORY_USAGE_GPU_ONLY)

~Texture ()

Texture (Texture &&other)

template <typename T>
void CopyFrom (const std::vector<T> &data)

template <typename T>
void CopyTo (std::vector<T> &data)

void CopyFrom (vk::CommandBuffer commandBuffer, Texture &srcImage)

void Barrier (vk::CommandBuffer commandBuffer, vk::ImageLayout oldLayout, vk::AccessFlags oldAccess, vk::ImageLayout newLayout, vk::AccessFlags newAccess)

vk::ImageView GetView () const

uint32_t GetWidth () const

uint32_t GetHeight () const

vk::Format GetFormat () const

void Clear (vk::CommandBuffer commandBuffer, const std::array<int, 4> &colour)

void Clear (vk::CommandBuffer commandBuffer, const std::array<float, 4> &colour)

```

Friends

```

friend Vortex2D::Renderer::GenericBuffer

class Timer
#include <Timer.h> Calculates the elapsed time on the GPU.

```

Public Functions

Timer (`const Device &device`)

`void Start (vk::CommandBuffer commandBuffer)`
Start the timer after the current last command buffer.

Parameters

- `commandBuffer`: command buffer to write timestamp

`void Stop (vk::CommandBuffer commandBuffer)`

Start the timer after the current last command buffer.

Parameters

- `commandBuffer`: command buffer to write timestamp

`void Start ()`

Start the timer after the current last command buffer.

`void Stop ()`

Stop the timer after the current last command buffer.

`void Wait ()`

Wait for `Start` and `Stop` to finish before retrieving the results.

`uint64_t GetElapsedNs ()`

Get the elapsed time between the Start and Stop calls. Blocking function which will download the timestamps from the GPU.

Return timestamp in nanoseconds.

struct Transformable

`#include <Transformable.h>` Class to represent the transformation of an object: position, scale, rotation and anchor.

Subclassed by `Vortex2D::Fluid::Circle`, `Vortex2D::Fluid::Polygon`, `Vortex2D::Fluid::RigidBody`, `Vortex2D::Renderer::AbstractShape`, `Vortex2D::Renderer::AbstractSprite`, `Vortex2D::Renderer::Ellipse`

Public Functions

Transformable ()

virtual ~Transformable ()

const glm::mat4 &GetTransform () const

Returns the transform matrix.

void Update ()

Update the transform matrix with the position, scale, rotation and anchor.

Public Members

property<glm::vec2> Position
absolute position

property<glm::vec2> Scale
scale for the x and y components

```

property<float> Rotation
    Rotation in radians.

property<glm::vec2> Anchor
    An offset to the position (used for centering a shape)

template <typename T>
class UniformBuffer: public Vortex2D::Renderer::GenericBuffer
    #include <Buffer.h> a uniform buffer type of buffer

```

Public Functions

```

UniformBuffer(const Device &device, VmaMemoryUsage memoryUsage = VMA_MEMORY_USAGE_GPU_ONLY)

template <typename T>
class VertexBuffer: public Vortex2D::Renderer::GenericBuffer
    #include <Buffer.h> a vertex buffer type of buffer

```

Public Functions

```

VertexBuffer(const Device &device, std::size_t size, VmaMemoryUsage memoryUsage = VMA_MEMORY_USAGE_GPU_ONLY)

class Work
    #include <Work.h> Represents a compute shader. It simplifies the process of binding, setting push constants and recording.

```

Public Functions

```

Work(const Device &device, const ComputeSize &computeSize, const SpirvBinary &spirv, const SpecConstInfo &additionalSpecConstInfo = {})
Constructs an object using a SPIRV binary. It is not bound to any buffers or textures.

```

Parameters

- *device*: vulkan device
- *computeSize*: the compute size. Can be a default one with size (1,1) or one with an actual size.
- *spirv*: binary spirv
- *additionalSpecConstInfo*: additional specialization constants

Work::*Bind*(**const** std::vector<*BindingInput*> &*inputs*)

Bind the buffers and/or textures.

Return a bound object, ready to be recorded in a command buffer.

Parameters

- *inputs*: a list of buffers and/or textures

VORTEX2D_API *Bound* *Vortex2D*::*Renderer*::*Work*::*Bind*(*ComputeSize* *computeSize*, **const** std::vector<*BindingInput*> &*inputs*)

Bind the buffers and/or textures. This overrides the provided compute size in *Work*.

Return a bound object, ready to be recorded in a command buffer.

Parameters

- *computeSize*: the compute shader compute size.
- *inputs*: a list of buffers and/or textures

class Bound

#include <Work.h> Is a bound version of [Work](#). This means a buffer or texture was bound and this can be recorded in a command buffer.

Public Functions

Bound()

template <typename ... Args>

void PushConstant (vk::CommandBuffer *commandBuffer*, Args&&... *args*)

Adds a constant value, i.e. a push constant.

Parameters

- *commandBuffer*: the command buffer where the compute work will also be recorded.
- *data*: the data to push. A total of 128 bytes can be used.

void Record (vk::CommandBuffer *commandBuffer*)

Record the compute work in this command buffer. This will also set two additional push constants: the 2D domain size.

Parameters

- *commandBuffer*: the command buffer to record into.

void RecordIndirect (vk::CommandBuffer *commandBuffer*, *IndirectBuffer*<*DispatchParams*> &*dispatchParams*)

Record the compute work in this command buffer. Use the provided parameters to run the compute shader.

Parameters

- *commandBuffer*: the command buffer to record into.
- *dispatchParams*: the indirect buffer containing the parameters.

Friends

friend Vortex2D::Renderer::Work

namespace Detail

Functions

void InsertSpecConst (*SpecConstInfo* &*specConstInfo*)

template <typename Arg, typename... Args>

void InsertSpecConst (*SpecConstInfo* &*specConstInfo*, Arg &&*arg*, Args&&... *args*)

1.2.7 Fluid API reference

Classes

- [Vortex2D::Fluid::Advection](#)
- [Vortex2D::Fluid::Circle](#)
- [Vortex2D::Fluid::ConjugateGradient](#)

- `Vortex2D::Fluid::Density`
- `Vortex2D::Fluid::Depth`
- `Vortex2D::Fluid::Diagonal`
- `Vortex2D::Fluid::DistanceField`
- `Vortex2D::Fluid::Extrapolation`
- `Vortex2D::Fluid::GaussSeidel`
- `Vortex2D::Fluid::IncompletePoisson`
- `Vortex2D::Fluid::Jacobi`
- `Vortex2D::Fluid::LevelSet`
- `Vortex2D::Fluid::LinearSolver`
- `Vortex2D::Fluid::LocalGaussSeidel`
- `Vortex2D::Fluid::Multigrid`
- `Vortex2D::Fluid::ParticleCount`
- `Vortex2D::Fluid::Polygon`
- `Vortex2D::Fluid::Preconditioner`
- `Vortex2D::Fluid::Pressure`
- `Vortex2D::Fluid::Rectangle`
- `Vortex2D::Fluid::Reduce`
- `Vortex2D::Fluid::ReduceJ`
- `Vortex2D::Fluid::ReduceMax`
- `Vortex2D::Fluid::ReduceSum`
- `Vortex2D::Fluid::RigidBody`
- `Vortex2D::Fluid::SmokeWorld`
- `Vortex2D::Fluid::Transfer`
- `Vortex2D::Fluid::Velocity`
- `Vortex2D::Fluid::WaterWorld`
- `Vortex2D::Fluid::World`

API Reference

`namespace Fluid`

Enums

`enum VelocityOp`

Operator when applying velocity to velocity field: add or set.

Values:

`Add`

Set

Functions

```
Renderer::ComputeSize MakeLocalSize (const glm::ivec2 &size)
```

```
VORTEX2D_API LinearSolver::Parameters Vortex2D::Fluid::FixedParams (unsigned iterations)
```

Create a linear solver parameters object with fixed solver type.

Return parameters

Parameters

- *iterations*: number of iterations to do

```
VORTEX2D_API LinearSolver::Parameters Vortex2D::Fluid::IterativeParams (float errorTolerance)
```

Create a linear solver parameters object, solver will continue until error tolerance is reached.

Return parameters

Parameters

- *errorTolerance*: tolerance to reach before exiting

```
template <typename Class>
```

```
void Vortex2D::Fluid::ForAll(std::vector<Class *> &elements, void(Class::*)() f)
```

Variables

```
{ Renderer::ColorBlendState blendState; blendState.ColorBlend .setBlendEnable(true) .setColorBlendOp(vk::BlendOp::eMax) .setSrcColorBlendFactor(vk::BlendFactor::eOne) .setDstColorBlendFactor(vk::BlendFactor::eOne) .setColorWriteMask(vk::ColorComponentFlagBits::eR); return blendState; }
```

```
{ Renderer::ColorBlendState blendState; blendState.ColorBlend .setBlendEnable(true) .setColorBlendOp(vk::BlendOp::eMin) .setSrcColorBlendFactor(vk::BlendFactor::eOne) .setDstColorBlendFactor(vk::BlendFactor::eOne) .setColorWriteMask(vk::ColorComponentFlagBits::eR); return blendState; }
```

```
VORTEX2D_API Renderer::Clear Vortex2D::Fluid::BoundariesClear = Vortex2D::Renderer::Clear({1000000000000000000ull})
```

class Advection

#include <Advection.h> Adverts particles, velocity field or any field using a velocity field.

Public Functions

```
Advection (const Renderer::Device &device, const glm::ivec2 &size, float dt, Velocity &velocity)
```

Initialize advection kernels and related object.

Parameters

- *device*: vulkan device
- *size*: size of velocity field
- *dt*: delta time for integration
- *velocity*: velocity field

```
void AdvectVelocity()  
    Self advect velocity.  
  
void AdvectBind(Density &density)  
    Binds a density field to be advected.  
  
Parameters  
    • density: density field  
  
void Advect()  
    Performs an advection of the density field. Asynchronous operation.  
  
void AdvectParticleBind(Renderer::GenericBuffer &particles, Renderer::Texture &levelSet,  
                        Renderer::IndirectBuffer<Renderer::DispatchParams> &dispatch-  
Params)  
    Binds particles to be advected. Also use a level set to project out the particles if they enter it.  
  
Parameters  
    • particles: particles to be advected  
    • levelSet: level set to project out particles  
    • dispatchParams: contains number of particles  
  
void AdvectParticles()  
    Advect particles. Asynchronous operation.
```

class Cfl

#include <Cfl.h> Calculates the CFL number of the velocity field. It's an indication on how to choose your time step size. Ideally, the time step should be smaller than the CFL number.

Public Functions

```
Cfl(const Renderer::Device &device, const glm::ivec2 &size, Velocity &velocity)
```

```
void Compute()  
    Compute the CFL number. Non-blocking.
```

```
float Get()  
    Returns the CFL number. Blocking.  
Return cfl number
```

class Circle : public Vortex2D::Renderer::Transformable, public Vortex2D::Renderer::Drawable
#include <Boundaries.h> Signed distance field of circle.**Public Functions**

```
Circle(const Renderer::Device &device, float radius, float extent = 10.0f)  
    Initialize the circle with radius and extend of signed distance.
```

```
Parameters  
    • device: vulkan device.  
    • radius: radius of circle.  
    • extent: extend how far from the circle the signed distance field is calculated.
```

```
void Initialize(const Renderer::RenderState &renderState)  
    Initialize the drawable for a particular state. This might include creating the correct pipeline. If it was already initialized, it will do nothing.
```

Parameters

- renderState: the state to initialize with.

```
void Update (const glm::mat4 &projection, const glm::mat4 &view)  
    Update the MVP matrix of the drawable.
```

Parameters

- projection: the projection matrix
- view: the view matrix

```
void Draw (vk::CommandBuffer commandBuffer, const Renderer::RenderState &renderState)  
    Draw for the given render state. This has to be initialized before.
```

Parameters

- commandBuffer: the command buffer to record into.
- renderState: the render state to use.

```
class ConjugateGradient : public Vortex2D::Fluid::LinearSolver
```

```
#include <ConjugateGradient.h> An iterative preconditioned conjugate linear solver. The preconditioner  
can be specified.
```

Public Functions

```
ConjugateGradient (const Renderer::Device &device, const glm::ivec2 &size, Precondi-  
tioner &preconditioner)
```

Initialize the solver with a size and preconditioner.

Parameters

- device: vulkan device
- size:
- preconditioner:

```
void Bind (Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Renderer::GenericBuffer &b,  
           Renderer::GenericBuffer &x)
```

Bind the buffers for the linear solver.

Parameters

- d: the diagonal of the matrix
- l: the lower matrix
- b: the right hand side
- x: the unknowns

```
void BindRigidbody (float delta, Renderer::GenericBuffer &d, RigidBody &rigidBody)
```

Bind rigidbody with the linear solver's matrix.

Parameters

- delta: solver delta
- d: diagonal matrix
- rigidBody: rigidbody to bind to

```
void Solve (Parameters &params, const std::vector<RigidBody *> &rigidbodies = {})
```

Solve iteratively solve the linear equations in data.

```
class Density : public Vortex2D::RenderTexture, public Vortex2D::Sprite
```

```
#include <Density.h> Density field, used to represent smoke swirling.
```

Public Functions

Density (**const** *Renderer::Device* &*device*, **const** *glm::ivec2* &*size*, *vk::Format* *format*)

Friends

```
friend Vortex2D::Fluid::Advection

class Depth
#include <Multigrid.h> Contains the sizes of the multigrid hierarchy.
```

Public Functions

Depth (**const** *glm::ivec2* &*size*)

Initialize with the finest size.

Parameters

- *size*: the base size.

int GetMaxDepth() const

The calculated depth of the multigrid.

Return the depth.

glm::ivec2 GetDepthSize(std::size_t i) const

Gets the depth for a given level.

Return the size

Parameters

- *i*: the level

class Diagonal : public Vortex2D::Fluid::Preconditioner

#include <Diagonal.h> *Diagonal* preconditioner. Simplest of preconditioner, useful to verify if the preconditioned conjugate gradient works.

Public Functions

Diagonal (**const** *Renderer::Device* &*device*, **const** *glm::ivec2* &*size*)

void Bind(Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Renderer::GenericBuffer &b, Renderer::GenericBuffer &x)
Bind the linear equation buffers.

Parameters

- *d*: the diagonal of the matrix
- *l*: the lower matrix
- *b*: the right hand side
- *x*: the unknown buffer

void Record(vk::CommandBuffer commandBuffer)

Record the preconditioner.

Parameters

- *commandBuffer*: the command buffer to record into.

```
class DistanceField : public Vortex2D::Renderer::AbstractSprite
#include <Boundaries.h> Sprite of a distance field.
```

Public Functions

```
DistanceField(const Renderer::Device &device, Renderer::RenderTexture &levelSet, float
scale = 1.0f)
```

Initialize the price with the level set and scale.

Parameters

- device: vulkan device
- levelSet: level set to use as sprite
- scale: scale of the level set

```
void Draw(vk::CommandBuffer commandBuffer, const Renderer::RenderState &renderState)
```

Draw for the given render state. This has to be initialized before.

Parameters

- commandBuffer: the command buffer to record into.
- renderState: the render state to use.

```
class Extrapolation
```

```
#include <Extrapolation.h> Class to extrapolate values into the neumann and/or dirichlet boundaries.
```

Public Functions

```
Extrapolation(const Renderer::Device &device, const glm::ivec2 &size, Renderer::GenericBuffer &valid, Velocity &velocity, int iterations = 10)
```

```
void Extrapolate()
```

Will extrapolate values from buffer into the dirichlet and neumann boundaries.

```
void ConstrainBind(Renderer::Texture &solidPhi)
```

Binds a solid level set to use later and constrain the velocity against.

Parameters

- solidPhi: solid level set

```
void ConstrainVelocity()
```

Constrain the velocity, i.e. ensure that the velocity normal to the solid level set is 0.

```
class GaussSeidel : public Vortex2D::Fluid::LinearSolver, public Vortex2D::Fluid::Preconditioner
#include <GaussSeidel.h> An iterative black and red successive over relaxation linear solver.
```

Public Functions

```
GaussSeidel(const Renderer::Device &device, const glm::ivec2 &size)
```

```
void Bind(Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Renderer::GenericBuffer &b,
Renderer::GenericBuffer &x)
```

Bind the buffers for the linear solver.

Parameters

- d: the diagonal of the matrix
- l: the lower matrix

- b: the right hand side
- x: the unknowns

```
void BindRigidbody (float delta, Renderer::GenericBuffer &d, RigidBody &rigidBody)
    Bind rigidbody with the linear solver's matrix.
```

Parameters

- delta: solver delta
- d: diagonal matrix
- rigidBody: rigidbody to bind to

```
void Solve (Parameters &params, const std::vector<RigidBody*> &rigidbodies = {})
    Iterative solving of the linear equations in data.
```

```
void Record (vk::CommandBuffer commandBuffer)
    Record the preconditioner.
```

Parameters

- commandBuffer: the command buffer to record into.

```
void Record (vk::CommandBuffer commandBuffer, int iterations)
    Record a determined number of iterations.
```

Parameters

- commandBuffer:
- iterations:

```
void SetW (float w)
    Set the w factor of the GS iterations : x_new = w * x_new + (1-w) * x_old.
```

Parameters

- w:

```
void SetPreconditionerIterations (int iterations)
    set number of iterations to be used when GS is a preconditioner
```

Parameters

- iterations:

```
class IncompletePoisson : public Vortex2D::Fluid::Preconditioner
#include <IncompletePoisson.h> Incomplete poisson preconditioner. Slightly better than a simple diagonal preconditioner.
```

Public Functions

```
IncompletePoisson (const Renderer::Device &device, const glm::ivec2 &size)
```

```
void Bind (Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Renderer::GenericBuffer &b,
Renderer::GenericBuffer &x)
    Bind the linear equation buffers.
```

Parameters

- d: the diagonal of the matrix
- l: the lower matrix
- b: the right hand side
- x: the unknown buffer

```
void Record (vk::CommandBuffer commandBuffer)
    Record the preconditioner.
```

Parameters

- commandBuffer: the command buffer to record into.

```
struct J
```

Public Members

```
glm::vec2 linear
```

```
float angular
```

```
class Jacobi : public Vortex2D::Fluid::Preconditioner
#include <Jacobi.h> An iterative jacobi linear solver.
```

Public Functions

```
Jacobi (const Renderer::Device &device, const glm::ivec2 &size)
```

```
void Bind (Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Renderer::GenericBuffer &b,
          Renderer::GenericBuffer &x)
```

Bind the linear equation buffers.

Parameters

- *d*: the diagonal of the matrix
- *l*: the lower matrix
- *b*: the right hand side
- *x*: the unknown buffer

```
void Record (vk::CommandBuffer commandBuffer)
```

Record the preconditioner.

Parameters

- commandBuffer: the command buffer to record into.

```
void Record (vk::CommandBuffer commandBuffer, int iterations)
```

```
void SetW (float w)
```

Set the w factor of the GS iterations : $x_{\text{new}} = w * x_{\text{new}} + (1-w) * x_{\text{old}}$.

Parameters

- *w*:

```
void SetPreconditionerIterations (int iterations)
```

set number of iterations to be used when GS is a preconditioner

Parameters

- *iterations*:

```
class LevelSet : public Vortex2D::Renderer::RenderTexture
```

```
#include <LevelSet.h> A signed distance field, which can be re-initialized. In other words, a level set.
```

Public Functions

```
LevelSet (const Renderer::Device &device, const glm::ivec2 &size, int reinitializeIterations =
```

```
                  100)
```

```
void Reinitialise()
    Reinitialise the level set, i.e. ensure it is a correct signed distance field.

void ExtrapolateBind(Renderer::Texture &solidPhi)
    Bind a solid level set, which will be used to extrapolate into this level set.
```

Parameters

- *solidPhi*:

```
void Extrapolate()
    Extrapolate this level set into the solid level set it was attached to. This only performs a single cell extrapolation.
```

struct LinearSolver

#include <LinearSolver.h> An interface to represent a linear solver.

Subclassed by *Vortex2D*::*Fluid*::*ConjugateGradient*, *Vortex2D*::*Fluid*::*GaussSeidel*

Public Functions

```
virtual ~LinearSolver()
```

```
virtual void Bind(Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Ren-
derer::GenericBuffer &b, Renderer::GenericBuffer &x) = 0
Bind the buffers for the linear solver.
```

Parameters

- *d*: the diagonal of the matrix
- *l*: the lower matrix
- *b*: the right hand side
- *x*: the unknowns

```
virtual void BindRigidbody(float delta, Renderer::GenericBuffer &d, RigidBody &rigid-
Body) = 0
Bind rigidbody with the linear solver's matrix.
```

Parameters

- *delta*: solver delta
- *d*: diagonal matrix
- *rigidBody*: rigidbody to bind to

```
virtual void Solve(Parameters &params, const std::vector<RigidBody*> &rigidbodies =
    {}) = 0
Solves the linear equations.
```

Parameters

- *params*: solver iteration/error parameters
- *rigidBodies*: rigidbody to include in solver's matrix

struct Data

#include <LinearSolver.h> The various parts of linear equations.

Public Functions

```
Data(const Renderer::Device &device, const glm::ivec2 &size, VmaMemoryUsage memo-
ryUsage = VMA_MEMORY_USAGE_GPU_ONLY)
```

Public Members

```
Renderer::Buffer<float> Diagonal
Renderer::Buffer<glm::vec2> Lower
Renderer::Buffer<float> B
Renderer::Buffer<float> X

struct Parameters
#include <LinearSolver.h> Parameters for an iterative linear solvers.
```

Public Types

enum SolverType

Run the solver a fixed number of step or until we reached a minimum error.

Values:

Fixed

Iterative

Public Functions

Parameters (*SolverType type*, unsigned *iterations*, float *errorTolerance* = 0.0f)

Construct parameters with max iterations and max error.

Parameters

- *type*: fixed or iterative type of solver
- *iterations*: max number of iterations to perform
- *errorTolerance*: solver stops when the error is smaller than this.

bool IsFinished (float *initialError*) **const**

Checks if we've reacched the parameters.

Return if we can stop the linear solver.

Parameters

- *initialError*: the initial error

void Reset ()

Sets the out error and out iterations to 0.

Public Members

SolverType Type

unsigned **Iterations**

float **ErrorTolerance**

unsigned **OutIterations**

float **OutError**

```
class LocalGaussSeidel : public Vortex2D::Fluid::Preconditioner  
#include <GaussSeidel.h> A version of the gauss seidel that can only be applied on sizes (16,16) or  
smaller.
```

Public Functions

```
LocalGaussSeidel(const Renderer::Device &device, const glm::ivec2 &size)

void Bind(Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Renderer::GenericBuffer &b,
           Renderer::GenericBuffer &x)
    Bind the linear equation buffers.
```

Parameters

- d: the diagonal of the matrix
 - l: the lower matrix
 - b: the right hand side
 - x: the unknown buffer

void Record(vk::CommandBuffer *commandBuffer*)
Record the preconditioner.

Parameters

- `commandBuffer`: the command buffer to record into.

```
class Multigrid : public Vortex2D::Fluid::Preconditioner
#include <Multigrid.h> Multigrid preconditioner. It creates a hierarchy of twice as small set of linear
equations. It applies a few iterations of jacobi on each level and transfers the error on the level above. It
then copies the error down, adds to the current solution and apply a few more iterations of jacobi.
```

Public Functions

Multigrid(*const Renderer::Device &device*, *const glm::ivec2 &size*, *float delta*)
Initialize multigrid for given size and delta.

Parameters

- `device`: vulkan device
 - `size`: of the linear equations
 - `delta`: timestep delta

**void Bind(Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Renderer::GenericBuffer &b,
 Renderer::GenericBuffer &x)**
Bind the linear equation buffers.

Parameters

- d: the diagonal of the matrix
 - l: the lower matrix
 - b: the right hand side
 - x: the unknown buffer

```
void BuildHierarchiesBind(Pressure &pressure, Renderer::Texture &solidPhi, Renderer::Texture &liquidPhi)
```

Parameters

- pressure: The current linear equations
 - solidPhi: the solid level set

- liquidPhi: the liquid level set

```
void BuildHierarchies()
```

Computes the hierarchy to be used by the multigrid. Asynchronous operation.

```
void Record(vk::CommandBuffer commandBuffer)
```

Record the preconditioner.

Parameters

- commandBuffer: the command buffer to record into.

```
struct Particle
```

Public Members

```
glm::vec2 Position
```

```
glm::vec2 Velocity
```

```
class ParticleCount : public Vortex2D::Renderer::RenderTexture
```

#include <Particles.h> Container for particles used in the advection of the fluid simulation. Also a level set that is built from the particles.

Public Functions

```
ParticleCount(const Renderer::Device &device, const glm::ivec2 &size, Renderer::GenericBuffer &particles, const Renderer::DispatchParams &params = {0}, float alpha = 1.0f)
```

```
void Scan()
```

Count the number of particles and update the internal data structures.

```
int GetTotalCount()
```

Calculate the total number of particles and return it.

Return

```
Renderer::IndirectBuffer<Renderer::DispatchParams> &GetDispatchParams()
```

Calculate the dispatch parameters to use on the particle buffer.

Return

```
void LevelSetBind(LevelSet &levelSet)
```

Bind a solid level set, which will be used to interpolate the particles out of.

Parameters

- levelSet:

```
void Phi()
```

Calculate the level set from the particles.

```
void VelocitiesBind(Velocity &velocity, Renderer::GenericBuffer &valid)
```

Bind the velocities, used for advection of the particles.

Parameters

- velocity:
- valid:

```

void TransferToGrid()
    Interpolate the velocities of the particles to the velocities field.

void TransferFromGrid()
    Interpolate the velocities field in to the particles' velocity.

class Polygon : public Vortex2D::Renderer::Transformable, public Vortex2D::Renderer::Drawable
    #include <Boundaries.h> Signed distance field of a polygon.

Subclassed by Vortex2D::Fluid::Rectangle

```

Public Functions

Polygon (const Renderer::Device &device, std::vector<glm::vec2> points, bool inverse = false, float extent = 10.0f)
 Initialize polygon with set of points and extent of signed distance.

Parameters

- device: vulkan device
- points: clockwise oriented set of points (mininum 3).
- inverse: flag if the distance field should be inversed.
- extent: extend how far from the poylon the signed distance field is calculated.

void Initialize (const Renderer::RenderState &renderState)

Initialize the drawable for a particular state. This might include creating the correct pipeline. If it was already initialized, it will do nothing.

Parameters

- renderState: the state to initialize with.

void Update (const glm::mat4 &projection, const glm::mat4 &view)

Update the MVP matrix of the drawable.

Parameters

- projection: the projection matrix
- view: the view matrix

void Draw (vk::CommandBuffer commandBuffer, const Renderer::RenderState &renderState)

Draw for the given render state. This has to be initialized before.

Parameters

- commandBuffer: the command buffer to record into.
- renderState: the render state to use.

struct Preconditioner

#include <Preconditioner.h> An interface to represent a linear solver preconditioner.

Subclassed by *Vortex2D::Fluid::Diagonal, Vortex2D::Fluid::GaussSeidel, Vortex2D::Fluid::IncompletePoisson, Vortex2D::Fluid::Jacobi, Vortex2D::Fluid::LocalGaussSeidel, Vortex2D::Fluid::Multigrid*

Public Functions

virtual ~Preconditioner()

```
virtual void Bind(Renderer::GenericBuffer &d, Renderer::GenericBuffer &l, Renderer::GenericBuffer &b, Renderer::GenericBuffer &x) = 0
```

Bind the linear equation buffers.

Parameters

- d: the diagonal of the matrix
- l: the lower matrix
- b: the right hand side
- x: the unknown buffer

```
virtual void Record(vk::CommandBuffer commandBuffer) = 0
```

Record the preconditioner.

Parameters

- commandBuffer: the command buffer to record into.

class PrefixScan

#include <PrefixScan.h> The prefix sum operator.

```
void PrefixSym(int input[], int n, int output[])
{
    output[0] = input[0];

    for (int i = 1; i < n; i++)
        output[i] = output[i-1] + input[i];
}
```

Public Functions

```
PrefixScan(const Renderer::Device &device, const glm::ivec2 &size)
```

```
PrefixScan::Bound Bind(Renderer::GenericBuffer &input, Renderer::GenericBuffer &output, Renderer::GenericBuffer &dispatchParams)
```

class Bound

#include <PrefixScan.h> A prefix scan object bound with input/output buffers, ready to be dispatched.

Public Functions

```
void Record(vk::CommandBuffer commandBuffer)
```

Friends

```
friend Vortex2D::Fluid::PrefixScan
```

class Pressure

#include <Pressure.h> build the linear equation and compute the divergence from the resulting solution.

Public Functions

```
Pressure(const Renderer::Device &device, float dt, const glm::ivec2 &size, LinearSolver::Data &data, Velocity &velocity, Renderer::Texture &solidPhi, Renderer::Texture &liquidPhi, Renderer::GenericBuffer &valid)
```

```
Renderer::Work::Bound BindMatrixBuild(const glm::ivec2 &size, Renderer::GenericBuffer
&diagonal, Renderer::GenericBuffer &lower,
Renderer::Texture &liquidPhi, Renderer::Texture
&solidPhi)
```

Bind the various buffes for the linear system $Ax = b$.

Return

Parameters

- size: size of the linear system
- diagonal: diagonal of A
- lower: lower matrix of A
- liquidPhi: liquid level set
- solidPhi: solid level set

```
void BuildLinearEquation()
```

Build the matrix A and right hand side b.

```
void ApplyPressure()
```

Apply the solution of the equation $Ax = b$, i.e. the pressure to the velocity to make it non-divergent.

```
class Rectangle : public Vortex2D::Fluid::Polygon
```

#include <Boundaries.h> Signed distance field of a rectangle.

Public Functions

```
Rectangle(const Renderer::Device &device, const glm::vec2 &size, bool inverse = false, float
extent = 10.0f)
```

Initialize rectangle with size and extent of signed distance.

Parameters

- device: vulkan device.
- size: rectangle size
- inverse: flag if the distance field should be inverted.
- extent: extent how far from the rectangle the signed distance field is calculated.

```
class Reduce
```

#include <Reduce.h> Parallel reduction of a buffer into one value. The operator and type of data is specified by inheriting the class.

Subclassed by `Vortex2D::Fluid::ReduceJ`, `Vortex2D::Fluid::ReduceMax`, `Vortex2D::Fluid::ReduceSum`

Public Functions

```
virtual ~Reduce()
```

```
Reduce::Bound Bind(Renderer::GenericBuffer &input, Renderer::GenericBuffer &output)
```

Bind the reduce operation.

Return a bound object that can be recorded in a command buffer.

Parameters

- input: input buffer
- output: output buffer

```
class Bound
```

#include <Reduce.h> `Bound` input and output buffer for a reduce operation.

Public Functions

Bound()

void **Record**(vk::CommandBuffer *commandBuffer*)

Record the reduce operation.

Parameters

- *commandBuffer*: the command buffer to record into.

Friends

friend Vortex2D::Fluid::Reduce

class ReduceJ : public Vortex2D::Fluid::Reduce

#include <Reduce.h> *Reduce* operation on a struct with a 2d vector and 1 float (i.e. 3 floats) with addition.

Public Functions

ReduceJ(const Renderer::Device &device, const glm::ivec2 &size)

Initialize reduce with device and 2d size.

Parameters

- *device*:
- *size*:

class ReduceMax : public Vortex2D::Fluid::Reduce

#include <Reduce.h> *Reduce* operation on float with max of absolute.

Public Functions

ReduceMax(const Renderer::Device &device, const glm::ivec2 &size)

Initialize reduce with device and 2d size.

Parameters

- *device*:
- *size*:

class ReduceSum : public Vortex2D::Fluid::Reduce

#include <Reduce.h> *Reduce* operation on float with addition.

Public Functions

ReduceSum(const Renderer::Device &device, const glm::ivec2 &size)

Initialize reduce with device and 2d size.

Parameters

- *device*:
- *size*:

class RigidBody : public Vortex2D::Renderer::Transformable

#include <Rigidbody.h> Rigidbody that can interact with the fluid: either be push by it, or influence it, or both.

Public Types

```
enum Type
    Values:
        eStatic = 0x01
        eWeak = 0x02
        eStrong = 0x3
```

Public Functions

RigidBody (**const Renderer::Device &device**, **const glm::ivec2 &size**, **Renderer::Drawable &drawable**, **vk::Flags<Type> type**)

~RigidBody ()

void ApplyForces ()

function to override and apply forces from this rigidbody to the external rigidbody

void ApplyVelocities ()

to override and apply velocities from the external rigidbody to the this rigidbody

void SetMassData (float mass, float inertia)

Sets the mass and inertia of the rigidbody.

Parameters

- **mass**: of the body
- **inertia**: of the body

void SetVelocities (const glm::vec2 &velocity, float angularVelocity)

sets the velocities and angular velocities of the body

Parameters

- **velocity**:
- **angularVelocity**:

void UpdatePosition ()

Upload the transform matrix to the GPU.

void RenderPhi ()

Render the current object orientation in an internal texture and the external one.

void BindPhi (Renderer::RenderTexture &phi)

Bind the rendertexture where this rigidbodies shape will be rendered.

Parameters

- **phi**: render texture of the world

void BindDiv (Renderer::GenericBuffer &div, Renderer::GenericBuffer &diagonal)

Bind a the right hand side and diagonal of the linear system $Ax = b$. This is to apply the rigid body influence to the system.

Parameters

- **div**: right hand side of the linear system $Ax=b$
- **diagonal**: diagonal of matrix A
- **fluidLevelSet**: fluid level set

```
void BindVelocityConstrain(Fluid::Velocity &velocity)
```

Bind velocities to constrain based on the body's velocity.

Parameters

- *velocity*:

```
void BindForce(Renderer::GenericBuffer &d, Renderer::GenericBuffer &pressure)
```

Bind pressure, to have the pressure update the body's forces.

Parameters

- *fluidLevelSet*: fluid level set, to know if the pressure is applicable
- *pressure*: solved pressure buffer

```
void BindPressure(float delta, Renderer::GenericBuffer &d, Renderer::GenericBuffer &s, Renderer::GenericBuffer &z)
```

Bind pressure, to have the pressure update the body's forces.

Parameters

- *delta*:
- *d*:
- *s*:
- *z*:

```
void Div()
```

Apply the body's velocities to the linear equations matrix A and right hand side b.

```
void Force()
```

Apply the pressure to body, updating its forces.

```
void Pressure()
```

Reduce the force for pressure update.

```
void VelocityConstrain()
```

Constrain the velocities field based on the body's velocity.

```
RigidBody::Velocity GetForces()
```

Download the forces from the GPU and return them.

Return

```
vk::Flags<RigidBody::Type> GetType()
```

Type of this body.

Return

```
Renderer::RenderTexture &Phi()
```

the local level set of the body

Return

```
struct Velocity
```

Public Members

```
glm::vec2 velocity
```

```
float angular_velocity
```

```
class RigidBodySolver
```

#include <Rigidbody.h> Interface to call the external rigidbody solver.

Public Functions

```
virtual void Step (float delta) = 0
    performs a single step of the solver.
```

Parameters

- *delta*: of simulation

```
class SmokeWorld : public Vortex2D::Fluid::World
```

#include <World.h> A concrete implementation of *World* to simulate ‘smoke’, or more accurately dye in a liquid. The liquid cannot change location or size.

Public Functions

```
SmokeWorld (const Renderer::Device &device, const glm::ivec2 &size, float dt)
```

```
void FieldBind (Density &density)
```

Bind a density field to be moved around with the fluid.

Parameters

- *density*: the density field

```
class Transfer
```

#include <Transfer.h> Prolongs or restrict a level set on a finer or coarser level set.

Public Functions

```
Transfer (const Renderer::Device &device)
```

Initialize prolongate and restrict compute pipelines.

Parameters

- *device*:

```
void ProlongateBind (std::size_t level, const glm::ivec2 &fineSize, Renderer::GenericBuffer
    &fine, Renderer::GenericBuffer &fineDiagonal, Renderer::GenericBuffer
    &coarse, Renderer::GenericBuffer &coarseDiagonal)
```

Prolongate a level set on a finer level set. Setting the 4 cells to the value of the coarser grid. Multiple level sets can be bound and indexed.

Parameters

- *level*: the index of the bound level set to prolongate
- *fineSize*: size of the finer level set
- *fine*: the finer level set
- *fineDiagonal*: the diagonal of the linear equation matrix at size *fineSize*
- *coarse*: the coarse level set
- *coarseDiagonal*: the diagonal of the linear equation matrix at size half of *fineSize*

```
void RestrictBind (std::size_t level, const glm::ivec2 &fineSize, Renderer::GenericBuffer
    &fine, Renderer::GenericBuffer &fineDiagonal, Renderer::GenericBuffer
    &coarse, Renderer::GenericBuffer &coarseDiagonal)
```

Restricting the level set on a coarser level set. Averages 4 cells into one. Multiple level sets can be bound and indexed.

Parameters

- *level*: the index of the bound level set to prolongate

- `fineSize`: size of the finer level set
- `fine`: the finer level set
- `fineDiagonal`: the diagonal of the linear equation matrix at size `fineSize`
- `coarse`: the coarse level set
- `coarseDiagonal`: the diagonal of the linear equation matrix at size half of `fineSize`

```
void Prolongate (vk::CommandBuffer commandBuffer, std::size_t level)
    Prolongate the level set, using the bound level sets at the specified index.
```

Parameters

- `commandBuffer`: command buffer to record into.
- `level`: index of bound level sets.

```
void Restrict (vk::CommandBuffer commandBuffer, std::size_t level)
    Restrict the level set, using the bound level sets at the specified index.
```

Parameters

- `commandBuffer`: command buffer to record into.
- `level`: index of bound level sets.

```
class Velocity : public Vortex2D::Renderer::RenderTexture
#include <Velocity.h> The Velocity field. Can be used to calculate a difference between different states.  
Contains three fields: input and output, used for ping-pong algorithms, and d, the difference between two velocity fields.
```

Public Functions

```
Velocity (const Renderer::Device &device, const glm::ivec2 &size)
```

Renderer::*Texture* &**Output** ()

An output texture used for algorithms that used the velocity as input and need to create a new velocity field.

Return

Renderer::*Texture* &**D** ()

A difference velocity field, calculated with the difference between this velocity field, and the output velocity field.

Return

```
void CopyBack (vk::CommandBuffer commandBuffer)
```

Copy the output field to the main field.

Parameters

- `commandBuffer`:

```
void Clear (vk::CommandBuffer commandBuffer)
```

Clear the velocity field.

Parameters

- `commandBuffer`:

```
void SaveCopy ()
```

Copy to the difference field.

```
void VelocityDiff ()
```

Calculate the difference between the difference field and this velocity field, store it in the difference field.

```
class WaterWorld : public Vortex2D::Fluid::World
#include <World.h> A concrete implementation of World to simulate water.
```

Public Functions

```
WaterWorld(const Renderer::Device &device, const glm::ivec2 &size, float dt, int numSub-
Steps)
```

```
Renderer::RenderCommand RecordParticleCount (Renderer::RenderTarget::DrawableList
drawables)
```

The water simulation uses particles to define the water area. In fact, the level set is built from the particles. This means to be able to set an area, we can't use *RecordLiquidPhi*. To define the particle area, simply draw a regular shape. The colour r is used to determine if we add or remove particles, use r = 4 to add and r = -4 to remove.

Return render command

Parameters

- **drawables**: list of drawables object with colour 8 or -8

```
class World
```

```
#include <World.h> The main class of the framework. Each instance manages a grid and this class is used
to set forces, define boundaries, solve the incompressibility equations and do the advection.
```

Subclassed by *Vortex2D::Fluid::SmokeWorld*, *Vortex2D::Fluid::WaterWorld*

Public Functions

```
World(const Renderer::Device &device, const glm::ivec2 &size, float dt, int numSubSteps = 1)
Construct an Engine with a size and time step.
```

Parameters

- **device**: vulkan device
- **size**: dimensions of the simulation
- **dt**: timestamp of the simulation, e.g. 0.016 for 60FPS simulations.
- **numSubSteps**: the number of sub-steps to perform per step call. Reduces loss of fluid.

```
virtual ~World()
```

```
void Step (LinearSolver::Parameters &params)
```

Perform one step of the simulation.

```
Renderer::RenderCommand RecordVelocity (Renderer::RenderTarget::DrawableList draw-
ables, VelocityOp op)
```

Record drawables to the velocity field. The colour (r,g) will be used as the velocity (x, y)

Return render command

Parameters

- **drawables**: a list of drawable field
- **op**: operation of the render: add velocity or set velocity

```
void SubmitVelocity (Renderer::RenderCommand &renderCommand)
```

submit the render command created with *RecordVelocity*

Parameters

- **renderCommand**: the render command

Renderer::RenderCommand **RecordLiquidPhi** (*Renderer::RenderTarget::DrawableList drawables*)

Record drawables to the liquid level set, i.e. to define the fluid area. The drawables need to make a signed distance field, if not the result is undefined.

Return render command

Parameters

- *drawables*: a list of signed distance field drawables

Renderer::RenderCommand **RecordStaticSolidPhi** (*Renderer::RenderTarget::DrawableList drawables*)

Record drawables to the solid level set, i.e. to define the boundary area. The drawables need to make a signed distance field, if not the result is undefined.

Return render command

Parameters

- *drawables*: a list of signed distance field drawables

DistanceField **LiquidDistanceField()**

Create sprite that can be rendered to visualize the liquid level set.

Return a sprite

DistanceField **SolidDistanceField()**

Create sprite that can be rendered to visualize the solid level set.

Return a sprite

void AddRigidbody (*RigidBody &rigidbody*)

Add a rigidbody to the solver.

Parameters

- *rigidbody*:

void RemoveRigidBody (*RigidBody &rigidbody*)

Remove a rigidbody from the solver.

Parameters

- *rigidbody*:

void AttachRigidBodySolver (*RigidBodySolver &rigidbodySolver*)

Attach a rigidbody solver, e.g. box2d.

Parameters

- *rigidbodySolver*:

float GetCFL()

Calculate the CFL number, i.e. the width divided by the max velocity.

Return CFL number

Renderer::Texture &**GetVelocity()**

Get the velocity, can be used to display it.

Return velocity field reference

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